# The Riemann problem Rarefaction waves and shock waves

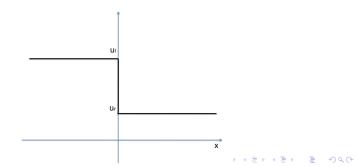
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## 1. An illuminating example

## ► A Heaviside function as initial datum

Solving the Riemann problem for the Hopf equation consists in describing the solutions to

$$\begin{cases} \partial_t u + \frac{1}{2} \partial_x u^2 = 0, \\ u_0(x) = u_l \text{ for } x \le 0, \quad u_0(x) = u_r \text{ for } x > 0. \end{cases}$$
(1)



## Scaling invariance

Let  $u \equiv u(t, x)$  be a solution of the (conservative) Hopf equation

$$\partial_t u + \frac{1}{2} \partial_x u^2 = 0 \,,$$

with initial data  $u_0$ . Then, for any  $\lambda \in \mathbb{R}$ ,  $u_\lambda \equiv u(\lambda t, \lambda x)$  is also a solution with initial data

$$u_{\lambda}(0,x) = u_0(\lambda x).$$

Note that, because of the homogeneity of the flux function, the Hopf equation admits other scaling invariances. But this is not a general feature of hyperbolic system of conservation laws.

## Self-similar solutions

Because of the scaling invariance of the equation and the particular form of the initial data, it is then natural to seek **self-similar solutions** of the form

$$u(t,x)=v\left(\frac{x}{t}\right)$$

The initial data prescribes the limiting values

$$\lim_{z\to-\infty} v(z) = u_l,$$
$$\lim_{z\to+\infty} v(z) = u_r.$$

The partial differential equation reduces to an **ordinary differential** equation (possibly in weak form to catch singularities).

## Glimm's approximation scheme

Solving the Riemann problem is not only an exercise. It is the elementary step to prove the **global existence of weak solutions** for 1D hyperbolic system of conservation laws.

A discrete scheme has been indeed proposed by Glimm to get **approximate solutions**.

For each time step nh 
ightarrow (n+1)h

- define spatial cells of size k
- choose (randomly) one point in each half interval
- compute the values of *u* at time *nh* at these two points
- solve Riemann's problem on each cell

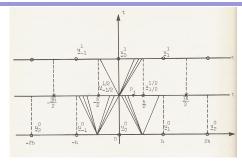


Fig. 2. Glimm's scheme

The convergence of this approximation scheme as  $h, k \rightarrow 0$  then requires to obtain

- a priori bounds (using the explicit wave profiles);
- **compactness** (coming from an additional bound on the interaction potential and the total variation).

Such a proof is beyond the scope of this lecture. For scalar equations, we will see (in the next parallel session) an alternative proof of existence based on some viscous approximation.

# $2. \ ``Smooth'' \ solutions: rarefaction \ waves\\$

## A simple ordinary differential equation

For "smooth" solutions, (1) can be rewritten

$$\begin{cases} -\frac{x}{t^2}v'\left(\frac{x}{t}\right) + \frac{1}{t}v\left(\frac{x}{t}\right)v'\left(\frac{x}{t}\right) = 0,\\ \lim_{z \to -\infty} v(z) = u_l, \quad \lim_{z \to +\infty} v(z) = u_r. \end{cases}$$
(2)

For continuous, piecewise  $C^1$  functions, the ordinary differential equation leads to the condition

$$v'(z) = 0 \text{ or } v(z) = z$$
.

The wave profile is then given by a combination of affine functions.

Note that the equation is not really satisfied in strong sense, insofar as the identity holds only **almost everywhere**.

#### We finally get a unique solution

$$v(z) = z \text{ if } z \in [u_l, u_r], \quad v(z) = u_l \text{ if } z \le u_l,$$
  
and  $v(z) = u_r \text{ if } z \ge u_r.$ 

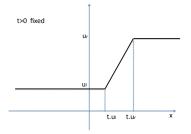


Fig. 3. Rarefaction wave

The rarefaction fans connect only states  $u_l$  and  $u_r$  such that

 $u_l \leq u_r$ .

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## Characteristics

#### The method of characteristics provides

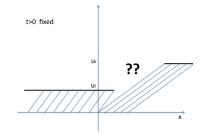


Fig. 4. Characteristics for the Riemann problem

**The problem is underdetermined**. We will see actually that there exist other weak solutions.

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## A singularity at time 0

A natural way to remove the uncertainty is to regularize the initial profile. Provided that the regularized data  $u_{0,\varepsilon}$  is monotonic increasing, there exists a global smooth solution. According to the previous lecture, we indeed have

$$t_{*,\varepsilon} = \frac{1}{\max_{x \in \mathbb{R}} (-u'_{0,\varepsilon}(x))_+} = +\infty.$$

It is therefore relevant to get an initial **singularity which does not propagate**, since - in a generalized sense -

$$\frac{1}{\max_{x\in\mathbb{R}}(-u_0'(x))_+}=+\infty\,.$$

## Conservation of entropies

Since the rarefaction profile v is a continuous, piecewise  $C^1$  solution of the Riemann problem (2), it is possible to multiply the ODE by F'(v) for any smooth F to get

$$-\frac{x}{t^2}F'\left(v\left(\frac{x}{t}\right)\right)v'\left(\frac{x}{t}\right)+\frac{1}{t}v\left(\frac{x}{t}\right)F'\left(v\left(\frac{x}{t}\right)\right)v'\left(\frac{x}{t}\right)=0,$$

In other words, denoting by G any function such that F'(z)z = G'(z),

$$\partial_t F\left(v\left(\frac{x}{t}\right)\right) + \partial_x G\left(v\left(\frac{x}{t}\right)\right) = 0.$$

The entropies are conserved, **the evolution is reversible** (as long as the initial time is not reached).

## 3. Discontinuous solutions : shock waves

## The Rankine-Hugoniot jump conditions

In the case when  $u_l > u_r$ , there is no continuous self-similar solution to the Riemann problem. A natural idea is then to weaken the differential condition, and to require that only an integral version of the conservation law is satisfied.

More precisely, we will search a solution in the form of a **Heaviside function** (like the initial data)

$$v(z) = u_l$$
 if  $z \leq s$ ,  $v(z) = u_r$  if  $z > s$ .

Simple computations then lead to the following jump condition

$$-s(u_r - u_l) + \frac{1}{2}(u_r^2 - u_l^2) = 0$$

referred to as Rankine-Hugoniot condition.

The **shock speed** *s* does not coincide with the velocity of particles : there is a kind of rearrangement process in order that the wave front is stable.

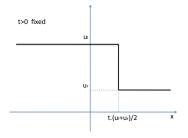


Fig. 5. Shock wave

The sound barrier is a well-known example of such a shock wave. It corresponds to the point at which an aircraft moves from transonic to supersonic speed.

## Characteristics

#### The method of characteristics provides

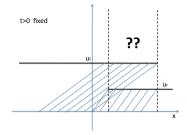


Fig. 5. Characteristics for the Riemann problem

**The problem is overdetermined**. We need a kind of averaging process to define weak solutions.

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## Lax-Oleinik's condition

Even if we regularize the initial profile, a singularity does appear for finite time

$$t_{*,arepsilon} = rac{1}{\max_{x\in\mathbb{R}}(-u_{0,arepsilon}'(x))_+} o 0 ext{ as } arepsilon o 0 \,.$$

In other words, singularities corresponding to decreasing discontinuities are stable.

We will actually see (in the next parallel session) that a natural condition for singular solutions to be admissible is the **Lax-Oleinik criterion** 

$$t\partial_x u \leq 1$$
,

which is inherited from the microscopic structure of the singularities.

### Decay of entropies

Let  $F(z) = \frac{1}{2}z^2$  and  $G(z) = \frac{1}{3}z^3$  be some associated flux, i.e. a function such that F'(z)z = G'(z). Straightforward computations lead to

$$-s(F(u_r) - F(u_l)) + (G(u_r) - G(u_l))$$
  
=  $-\frac{1}{2}(u_r + u_l)(F(u_r) - F(u_l)) + (G(u_r) - G(u_l))$   
=  $(u_r - u_l)(-\frac{1}{4}(u_r^2 + u_l^2 + 2u_ru_l) + \frac{1}{3}(u_r^2 + u_ru_l + u_l^2))$   
=  $(u_r - u_l)(\frac{1}{12}(u_r^2 + u_l^2) - \frac{1}{6}u_ru_l) < 0$ 

Note that a similar argument holds for any convex entropy.

The mathematical entropy (which is the opposite of the physical entropy) is therefore a decreasing function of time. **The evolution is irreversible**.